

TITLE: STEMS AND METHODS WITH INTE TED GPS AND DEAD RECKONING CAPABILITIES INVENTORS NAME: Thomas H. Walters et al.

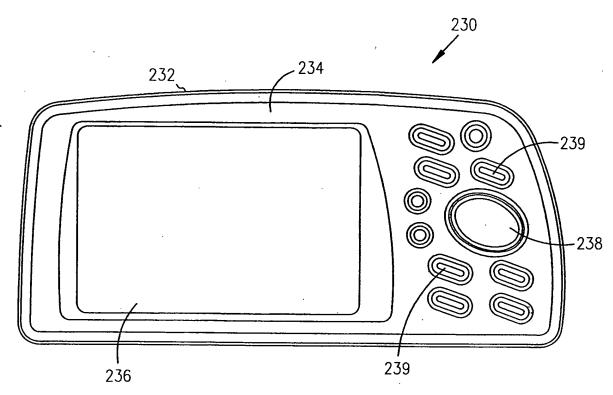


FIG. 2A

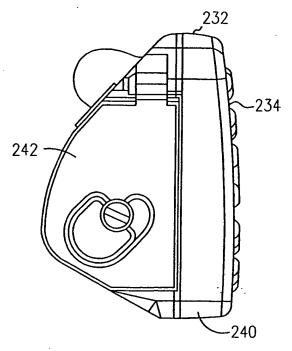
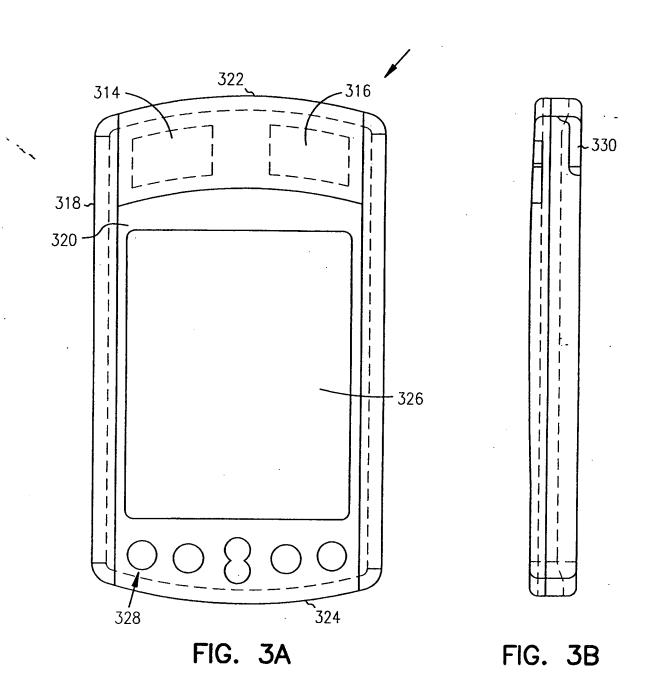


FIG. 2B

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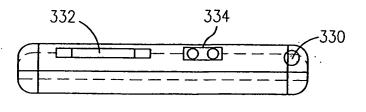


FIG. 3C

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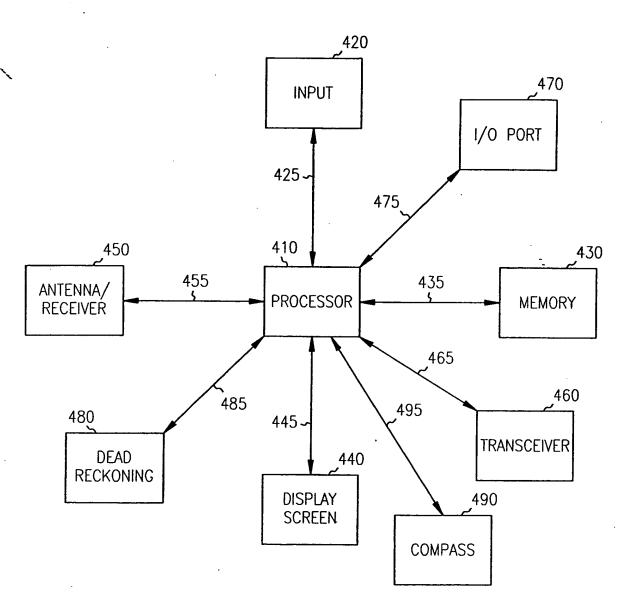


FIG. 4A

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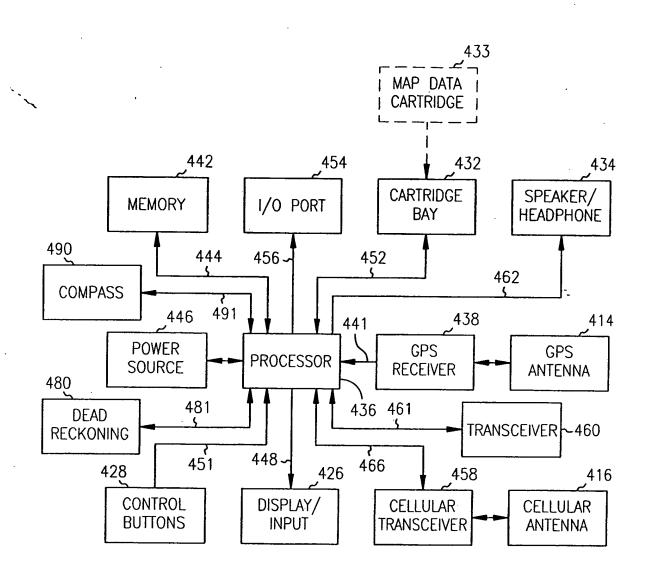


FIG. 4B

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TITLE: 'STEMS AND METHODS WITH INTE ATED GPS AND DEAD RECKONING CAPABILITIES INVENTORS NAME: Thomas H. Walters et al.

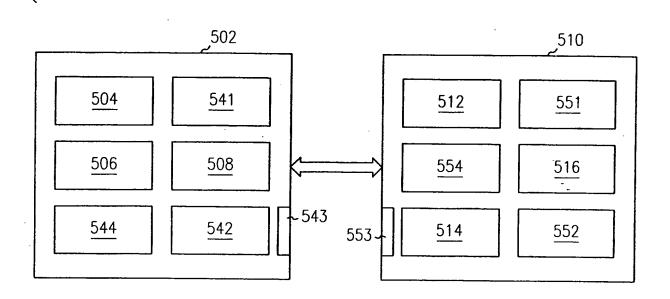
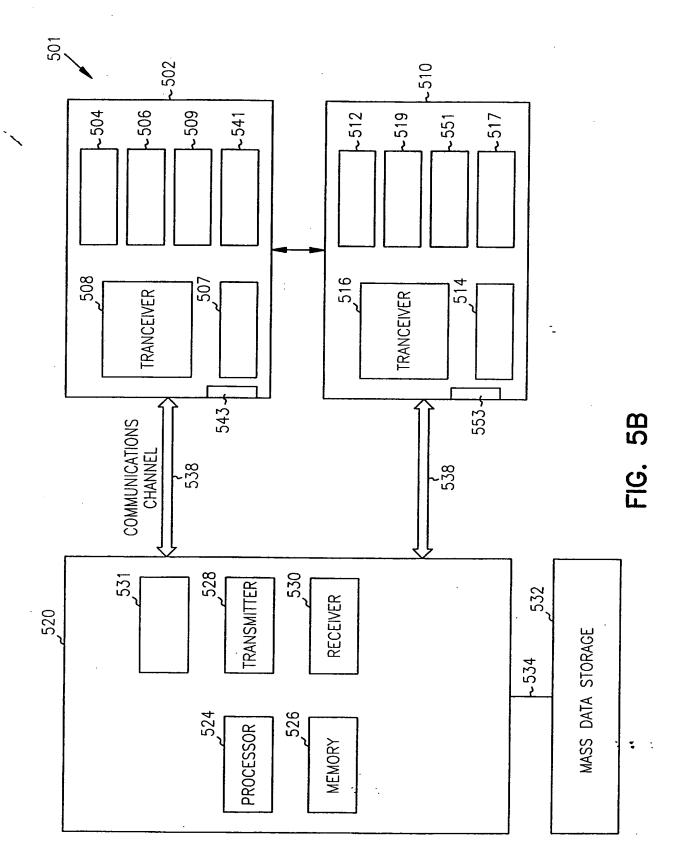


FIG. 5A

TITLE. SYSTEMS AND METHODS WITH INTEGRATED GPS AND DEAD RECKONING CAPABILITIES INVENTORS NAME: Thomas H. Walters et al.

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TITLE: 'STEMS AND METHODS WITH INTE: ATED GPS AND DEAD RECKONING CAPABILITIES INVENTORS NAME: Thomas H. Walters et al.

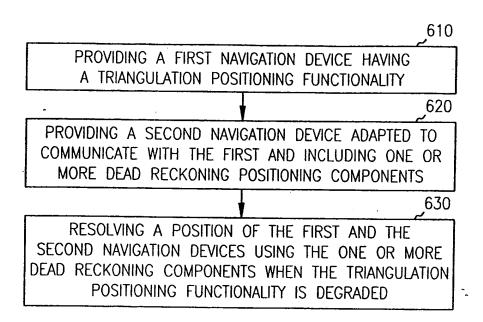


FIG. 6

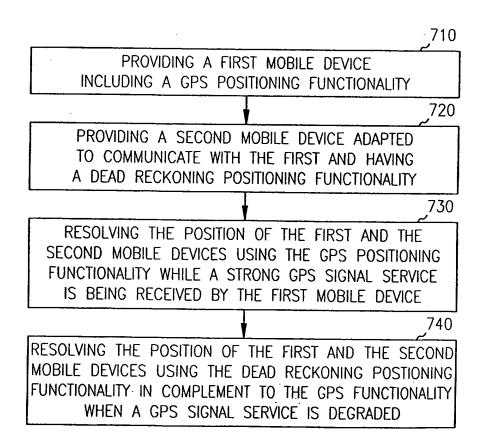


FIG. 7

TITLE:

STEMS AND METHODS WITH INTE TED GPS AND

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810

PERFORMING A ROUTE CALCULATION USING SOFTWARE OPERABLE ON A FIRST NAVIGATION DEVICE HAVING A TRIANGULATION FUNCTIONALITY

820

TRACKING A LOCATION OF THE FIRST NAVIGATION DEVICE USING THE TRIANGULATION POSITIONING FUNCTIONALITY AND THE DEAD RECKONING POSITIONING FUNCTIONALITY

840

WHEN TRACKING THE LOCATION OF THE FIRST NAVIGATION DEVICE IS DEGRADED, USING A SECOND NAVIGATION DEVICE, INCLUDING A DISTANCE DETERMINATION COMPONENT AND A ORIENTATION COMPONENT TO CONTINUE TRACKING THE LOCATION

FIG. 8